Reliability and Sensitivity Analysis of a Batch Arrival Retrial Queue with k-Phase Services, Feedback, Vacation, Delay, Repair and Admission

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Abstract

Queueing theory is a way for real-world problems modeling and analyzing. In many processes, the input is converted to the desired output after several successive steps. But usually limitations and conditions such as Lack of space, feedback, vacation, failure, repair, etc. have a great impact on process efficiency. This article deals with the modeling the steady-state behavior of $aM^X/G/I$ retrial queueing system with k phases of service. The arriving batches join the system with dependent admission due to the server state. If the customers find the server busy, they join the orbit to repeat their request. Although, the first phase of service is essential for all customers, any customer has three options after the completion of the i-th phase (i=1,2,...,k). They may take the (i+1)-th phase of service with probability θ_i , otherwise return the orbit with probability p_i or leave the system with probability $(1-p_i-\theta_i)$. Also, after each phase, the probabilistic failure, delay, repair and vacation are considered. In this article, after finding the steady-state distributions, the probability generating functions of the system and orbit size have been found. Then, some important performance measures of the system have been derived. Also, the system reliability has been defined. Eventually, to demonstrate the capability of the proposed model, the sensitivity analysis of performance measures via some model parameters (arrival/retrial/vacation rate) in different reliability levels have been investigated in a specific case of this model. Additionally, for optimizing the performance of system, some technical suggestions are presented.

Keyword:Bernoulli vacation, Feedback, Performance measures, Retrial queue, State-dependent admission, Repair, Delay, Reliability

Introduction

One way to identify the behavior of the systems in order to control and increase their productivity is to determine the model that they follow. On the other hand, without considering the priorities, real conditions and possible limitations for a system, the model fitting will not have the necessary efficiency. Today, increasing satisfaction of the customers is one of the most important priorities of dynamic systems. Sometimes, the customers arrive to the systems individually and sometimes in batches to receive services. For example, the sent products to the inspection test unit can be mentioned. In many systems, such as production of lines, achieving the desired result occurs after a multi-steps process. On the other hand, any system faces some limitations. One of these limitations is the lack of space for customers. In this case, the server is not ready to serve the customer at the

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moment of arrival. Therefore, considering another space (called the orbit) for new customers to repeat their requests from there is one solution for this problem. This is known as the retrial phenomenon. Another constraint islimited resources and facilities. These systems have to impose restrictions on customer admission according to their conditionsdue to the state of the server (idle/busy). Also, dissatisfaction with the results of each step leads to incomplete process for reasons such as returning the customer to orbit for reservice or leaving the system. Sometimes the system has to be refreshed by going on a vacation. On the other hand, system failure, especially when it is not possible to repair the system immediately, and the increasing cost and time can't be neglected. Since reducing time and cost is one of the most important factors in customer satisfaction, overcoming these limitations is essential for the survival of the system. One of the useful techniques for modeling the systems and determining its performance measures (such as the mean of customers in the system and orbit and their waiting times) is the

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queueing theory. On the other hand, the reliability assessment is an effective approach to maintain and enhance the quality of the process output, increasing customer satisfaction and market share in the competitive world today. So far, many studies have been done by scientists in this regard. Some of them are as follows:

The optimizing of the phoneconversations in a call center by Erlang [1] was the first experience of using the queueing theory.

Afterward, the retrial queueing models have been investigated by several researchers such as Falin and Templeton [2]. Also, a literature of the investigations about the retrial queues has been presented by Artalejo [3].

Besides, the batch arrival of the customers has been studied by many researchers. Falin [4], Kulkarni [5] and Yamamuro [6] are some examples of this subject.

Some of the studied retrial queueing models have several essential or optional phases of services. Some of the works in this area have been done in this area are Kumar et al. [7], Choudhury and Deka [8], Wang and Li [9], Maurya [10], Jeganathan et al. [11], Rao et al. [12].

Also, returning to the orbit (feedback) is considered in many of the studied systems. For example, Kumar et al. [16], Choudhury and Paul [13], Arivudainambi and Godhandaraman [14], BadamchiZadeh [15], Som and Seth [16], Rajadurai et al. [17], Bouchentouf et al. [18] have considered the feedback assumption in their models.

On the other hand, depending on the situation, different systems face different types of vacations, such as general vacation by Senthikumar and Arumuganathan[19], modified vacation by Jain and Bhagat[20], Bernoulli vacation by Choudhury and Ke[21], working vacation by Azhagappan[22] and variant vacation by Ke[23].

Occurrence of the breakdown/failure is the inevitable issue for any system. Therefore, in designing any system, preventive or corrective actions should be planned. So, the breakdowns/failures repair is one of the most important topics in this program. Therefore, this issue has been considered in many of the studied systems such as V. G. Kulkarni and Bong Dae Choi [24] and P.Rajaduraia et al. [25].

But sometimes due to some limitations, these repairs are delayed.Madhu Jain and AmitaBhagat [26] and Choudhury and Ke[21] have been considered this issue in their model.

Some systems aren't able to respond to all customers. So, they have to impose restrictions on customer admission according to their conditions due to the state of the server (idle/busy). In this relation, Choudhury and Deka [27-28] have considered the Bernoulli admission mechanism in their model.

Improving the system reliability is one way to achieve the secure system. The reliability of multi-

component systems was studied by Birnbaun et al. [29]. Also, these subjects have been considered in the queueing models by some authors such as Li et al. [30], Tang [31], Wang et al. [32] and Achcar and Piratelli[33].

In this article, modeling and analyzing $aM^X/G/1$ retrial queue system with k-phases of heterogeneous services in succession with first essential and k-1 optional phases, and state-dependent admission have been studied. Also, after each phase, the probabilistic feedback, failure, delay, repair, and vacation have been considered. Also, by considering the successful delivery of all service stages as the system successful, the conception of reliability has been defined and the reliability analysis hasbeen done. Of course, there exist the other definitions of the concept of reliability for other models which can be referred to [34-36].

Despite many valuable studies, any system has not been studied with these conditions. The novelties of this article are considering all of the above conditions in a system together, modeling and obtaining the performance measures of the system and reliability and sensitivity analysis of a special case of it. In this relation, the queueingmethod for modeling and analysis of systems with process approaches hasbeen considered. This model is applicable in many processes such as telecommunication systems, telephone switching systems, computer networks, and inspection tests of products.

For this model, the steady-state distributions, the probability generating functions of the system and orbit size have been found. Then, the performance measures have been obtained by using the supplementary variable technique.

In summarizing, the main contributions of this article are as below:

- 1) Considering batch arrival, state-dependent admission and (after each phase) the probabilistic feedback, failure, delay, repair, and vacation conditions together in a k-phases retrial queueing system with first essential and k-1 optional phases,
- 2) Having three choices for customers after i th phase (i = 1, 2, ..., k 1)
 - i. going to (i + 1) th phase service with probability $\theta_i(\theta_k = 0)$,
 - ii. going to orbit with probability p_i ,
 - iii. leaving the system with probability $(1 p_i \theta_i)$,
- 3) Considering general assumptions such as arbitrary distributions of retrial/service times, different probabilities at each phase, and variable size of arrival batches to have a comprehensive model to contain different systems in special cases,
- 4) Considering the system reliability and its effect in sensitivity analysis,

- 5) Providing an applicable example in the engineering field with technical suggestions,
- Using the queueing method for modeling and analysis of the systems with process approach.

This paper is organized as follows. The model description is given in section 2. Section 3 deals with the analysis of the system containing the definitions, steady-state equations, and PGF[†]s. The PGFs of the system and orbit size and some important performance measures are obtained in section 4. Eventually, in section 5, by some numerical examples, the sensitivity of some performance measures is investigated. Also, the conclusions are provided in the section 6.

Model Description

The considered retrial queue has the following assumptions:

- A. The customers arrive in batches from outside the system according to a Poisson process with arrival rate λ with admission depending to the state of server. So, the probabilities of arrival are α_1 when the server is idle, α_2 when the server is busy, α_3 when the server is on vacation, α_4 when the server is in delay and α_5 when the server is under repair. The probability mass function (p.m.f.) of the size of batches is $c_m = \Pr(X = m)$; $m \ge 1$, with PGF $C(z) = E[z^X]$ and the first two factorial moments $C_{[1]}$ and $C_{[2]}$ are finite.
- B. There is no waiting space and if the server is busy, the arriving batches enter a retrial group (orbit) to repeat the request for service with the FCFS discipline. Otherwise, one customer of the arriving batch takes the service and the others enter the orbit.
- C. If an arriving customer (primary or retrial) finds the server idle, then he/she/it enters immediately to take the first phase of service. The concept of the primary customer is the customer who has arrived to the system for the first time.
- D. The retrial times are generally distributed with distribution function A(x), density function a(x) and Laplace transform $A^*(\theta)$. Also, the first and second moments of this distribution are finite.
- E. The server provides k phases of heterogeneous services in succession. The first phase is essential for all customers. At the end of i-th phase of service (i=1,2,...,k-1), the customer may take the (i+1)-th phase with probability θ_i , return to orbit to repeat the

retrial to take the service again with probability p_i or depart the system with probability $1 - \theta_i - p_i$. The service times are independent and for i - th phase denoted by the random variable B_i with general distribution functions $B_i(x)$, density functions $b_i(x)$ and Laplace transforms $B_i^*(\theta)(i = 1, 2, ..., k)$. Also, the first and second moments of these distributions are finite.

- F. At the end of i thphase (i = 1, 2, ..., k), if the applicant does not go to (i + 1) th phase the server can have a vacation with probability τ_i or may continue the new service with probability $1 \tau_i$. Vacation times are random variables with general distribution function $V_i(x)$, density function $v_i(x)$ and Laplace transform $V_i^*(\theta)$. The first and second moments of this distribution are finite.
- G. The server may fail at any phase. The life of the equipment used for the i-th phase service has an exponential distribution with parameter $1/a_i$, (i = 1,2,...,k).
- H. The delay time that occurred from the time of failure of the system to the time of repair at i-th phase (i=1,2,...,k) has a random variable D_i with general distribution functions $D_i(x)$, density functions $d_i(x)$ and Laplace transforms $D_i^*(\theta)(i=1,2,...,k)$. Also the first and second moments of these distributions are finite.
- I. The repair time of the system faced with failure in the i-th phase has a random variable R_i with general distribution functions $R_i(x)$, density functions $r_i(x)$ and Laplace transforms $R_i^*(\theta)(i=1,2,...,k)$. Also the first and second moments of these distributions are finite.

Analysis of the model

To analyze the model, first, the state of the system is recognized. Since the distribution of the service times is unknown (general), thus, this model doesn't hasthe Markovian property. But, an embedded Markov chain can be defined.

For this, the state of the system at time t by the Markov process $Z(t) = \{N(t), X(t)\}$ is considered, in which for $1 \le i \le k$:

$$J(t) = \begin{cases} 1 & \text{the server is idle} \\ 2 & \text{the server is busy at phase i} \\ 3 & \text{the server ison vacation at phase i} \\ 4 & \text{the server is in delay at phase i} \\ 5 & \text{the server is under repair at phase i} \end{cases}$$

and

[†] Probability generating functions

$$X(t) = \begin{cases} A^{0}(t) & J(t) = 1\\ B_{i}^{0}(t) & J(t) = 2\\ V_{i}^{0}(t) & J(t) = 3\\ D_{i}^{0}(t) & J(t) = 4\\ R_{i}^{0}(t) & J(t) = 5 \end{cases}$$
 (2)

Also,N(t) corresponds the number of customers in the retrial queue at time t.

Definition 1 For i = 1, 2, ..., k,

a) The service conditional completion rates at time x is

$$\mu_i(x) = b_i(x)/(1 - B_i(x))$$

by assumptions $B_i(0) = 0$, $B_i(\infty) = 1$ and that $B_i(x)$ (i = 1, 2, ..., k) are continuous at x = 0.

b) The vacation conditional completion rates at time *x* is

$$v_i(x) = v_i(x)/(1 - V_i(x))$$

by assumptions $V_i(0) = 0$, $V_i(\infty) = 1$ and that $V_i(x)$ ($i = 1, 2, ..., k$) are continuous at $x = 0$.

c) The delay conditional completion rates at time x is

$$\gamma_i(y) = \mathrm{d}_i(y)/(1-D_i(y))$$

by assumptions $D_i(0) = 0, D_i(\infty) = 1$ and that $D_i(y)(i=1,2,...,k)$ are continuous at $y=0$.

d) The repair conditional completion rates at time x is

$$\varepsilon_i(y) = g_i(y)/(1 - G_i(y))$$

by assumptions $G_i(0) = 0$, $G_i(\infty) = 1$ and that $G_i(y)(i = 1, 2, ..., k)$ are continuous at $y = 0$.

e) The repeated attempts (retrial) rate at time x is

$$\eta(x) = a(x)/(1 - A(x))$$

where $A(0) = 0$, $A(\infty) = 1$ and $A(x)$ is continuous at $x = 0$.

Definition2The reliability function of the system/applicants is defined as:

$$RE = q_k.RE_{k-1} \tag{2}$$

where

$$\begin{array}{ll} RE_i = \prod_{j=1}^i \theta_j & i=1,2,\ldots k \\ ; & RE_k = 0. \end{array} ; \quad RE_0 = \theta_0 = 1$$

According to the stated points in this section, the theory of the model can be extended in the following.

First, the stationary distribution of the Markovprocess $\{Z(t); t \ge 0\}$ under the stability condition is found. For this goal, the bellow probabilities are defined:

$$I_0(t) = p\{X(t) = A^0(t), N(t) = 0\}$$
(3)

$$\lim_{t \to \infty} I_0(t) = I_0 \tag{4}$$

where J(t) and N(t) have been defined before and the probability densities are:

$$I_n(t,x) = p\{X(t) = A^0(t), N(t) = n, x \le A^0(t) < x + dx\}, t \ge 0, x \ge 0, n \ge 1$$
 (5)

$$\lim_{t \to \infty} I_n(t, x) = I_n(x), \ \ x \ge 0, n \ge 1$$
 (6)

and for
$$i = 1, ..., k$$
,

$$P_{i,n}(t,x) = p\{X(t) = B_i^0(t), N(t) = n, x \le B_i^0(t)$$

$$< x + dx \quad \}, \quad t \ge 0, x \ge 0, n \quad (7)$$

$$\ge 0$$

$$\lim_{t \to \infty} P_{i,n}(t,x) = P_n(x), \ x \ge 0, n \ge 0, i = 1,2,...,k$$
 (8)

$$V_{i,n}(t,x) = p\{X(t) = V_i^0(t), N(t) = n, x \le V_i^0(t)$$

$$< x + dx \},$$

$$t \ge 0, x \ge 0, n \ge 0$$
(9)

$$\lim_{t \to \infty} V_{i,n}(t,x) = V_{i,n}(x), x \ge 0, n \ge 0$$
(10)

$$D_{i,n}(t,x,y) = p\{X(t) = D_i^0(t), N(t) = n, y \le D_i^0(t) < y + dy | B_i^0(11) \ge 0, y \ge 0, x \ge 0, n \ge 0$$

$$\lim_{t \to \infty} D_{i,n}(t, x, y) = D_{i,n}(x, y), y \ge 0, x \ge 0, n \ge 0$$
 (12)

$$D_{i,n}(t,x,y) =$$

$$p\{X(t) = D_i^0(t), N(t) = n, y \le D_i^0(t) < y + dy | B_i^0(t) = x\}$$

$$t \ge 0, y \ge 0, x \ge 0, n \ge 0$$
 (13)

$$\lim_{t \to \infty} R_{i,n}(t, x, y) = R_{i,n}(x, y), y \ge 0, x \ge 0, n \ge 0$$
 (14)

Now, by using the supplementary variable technique the steady state equations can be obtained for i = 1, ..., k as follow:

$$\lambda I_0 = \sum_{i=1}^{k-1} (1 - \theta_i - p_i)(1 - \tau_i) \int_0^\infty \mu_i(x) P_{i,0}(x) dx + \int_0^\infty \nu_i(x) V_{i,0}(x) dx$$
(15)

$$dP_{i,0}(x)/_{dx} + (\lambda + \mu_i(x) + a_i)P_{i,0}(x) = \lambda(1 - \alpha_2)P_{i,0}(x) + \int_0^\infty \varepsilon_i(y)R_{i,0}(x,y)dy$$
 (17)

$$dP_{i,n}(x)/dx + (\lambda + \mu_i(x) + a_i)P_{i,n}(x)$$

$$= \lambda(1 - \alpha_2)P_{i,n}(x) + \lambda\alpha_2 \sum_{m=1}^{n} c_m P_{i,n-m}(x)$$

$$+ \int_0^\infty \varepsilon_i(y)R_{i,n}(x,y)dy \qquad n \ge 1$$
(18)

$$(dV_{-}(i,0)(x)) / dx + (\lambda + \nu_{-}i(x)) V_{-}(i,0)(x)$$

$$= \lambda(1 - \alpha_{-}3) V_{-}(i,0)(x)$$
(19)

$$dV_{i,n}(x)/dx + (\lambda + \nu_i(x))V_{i,n}(x)$$

$$= \lambda(1 - \alpha_3)V_{i,n}(x)$$

$$+ \lambda\alpha_3 \sum_{m=1}^{n} c_m V_{i,n-m}(x) \qquad n \ge 1$$
(20)

$$dD_{i,0}(x,y)/dy + (\lambda + \gamma_i(y))D_{i,0}(x,y) = \lambda(1 - \alpha_4)D_{i,0}(x,y)$$
(21)

$$dD_{i,n}(x,y)/dx + (\lambda + \gamma_i(y))D_{i,n}(x,y)$$

$$= \lambda(1 - \alpha_4)D_{i,n}(x,y)$$

$$+ \lambda\alpha_4 \sum_{m=1}^{n} c_m D_{i,n-m}(x,y) \qquad n \ge 1$$
(22)

$$dR_{i,0}(x,y)/dy + (\lambda + \varepsilon_i(y))R_{i,0}(x,y)$$

= $\lambda(1 - \alpha_5)R_{i,0}(x,y)$ (23)

$$dR_{i,n}(x,y)/dx + (\lambda + \varepsilon_i(y))R_{i,n}(x,y)$$

$$= \lambda(1 - \alpha_5)R_{i,n}(x,y)$$

$$+ \lambda\alpha_5 \sum_{m=1}^{n} c_m R_{i,n-m}(x,y) \qquad n \ge 1$$
(24)

in which for i = 1, 2, ..., k, the boundary conditions are as below:

$$I_{n}(0) = \sum_{i=1}^{k} (1 - \tau_{i}) p_{i} \int_{0}^{\infty} \mu_{i}(x) P_{i,n-1}(x) dx$$

$$+ \sum_{i=1}^{k} (1 - \tau_{i}) (1 - \theta_{i} - p_{i}) \int_{0}^{\infty} \mu_{i}(x) P_{i,n}(x) dx$$

$$+ \sum_{i=1}^{k} \int_{0}^{\infty} \nu_{i}(x) V_{i,n}(x) dx, n$$

$$\geq 1$$
(25)

$$P_{1,0}(0) = \lambda c_1 I_0 + \int_0^\infty I_1(x) \eta(x) dx,$$
 (26)

$$P_{1,n}(0) = \lambda c_{n+1} I_0 + \lambda \alpha_1 \sum_{m=1}^{n} c_m \int_0^{\infty} I_{n-m+1}(x) dx$$

$$+ \int_0^{\infty} \eta(x) I_{n+1}(x) dx, \qquad n \ge 1$$
(27)

$$P_{i,n}(0) = \theta_{i-1} \int_0^\infty P_{i-1,n}(x) \mu_{i-1}(x) dx,$$

$$n \ge 1 \quad , i = 2, ..., k$$
(28)

$$V_{i,0}(0) = \tau_i (1 - \theta_i - p_i) \int_0^\infty \mu_i(x) P_{i,0}(x) dx,$$
 (29)

$$V_{i,n}(0) = \tau_i p_i \int_0^\infty P_{i,n-1}(x) \mu_i(x) dx + \int_0^\infty \tau_i (1 - \theta_i - p_i) P_{i,n}(x) \mu_i(x) dx \qquad n$$
 \geq 1

$$D_{i,n}(x,0) = a_i P_{i,n}(x) \tag{31}$$

$$R_{i,n}(x,0) = \int_0^\infty \gamma_i(y) D_{i,n}(x,y) dy$$
 (32)

and the normalized condition is

$$I_{0} + \sum_{n=1}^{\infty} \int_{0}^{\infty} I_{n}(x) dx + \sum_{n=0}^{\infty} \sum_{i=1}^{k} \left\{ \int_{0}^{\infty} P_{i,n}(x) dx + \int_{0}^{\infty} V_{i,n}(x) dx + \int_{0}^{\infty} \int_{0}^{\infty} D_{i,n}(x) dx dy + \int_{0}^{\infty} \int_{0}^{\infty} R_{i,n}(x) dx dy \right\}$$
(33)

Now, the PGFs are defined as below:

$$I(x,z) = \sum_{n=1}^{\infty} I_n(x)z^n,$$
 (34)

$$I(0,z) = \sum_{n=1}^{\infty} I_n(0)z^n,$$
(35)

$$P_{i}(x,z) = \sum_{n=0}^{\infty} P_{i,n}(x)z^{n},$$

$$i = 1,2,\dots,k$$
(36)

$$P_{i}(0,z) = \sum_{n=0}^{\infty} P_{i,n}(0)z^{n},$$

$$i = 1,2,\dots,k$$
(37)

$$V_{i}(x,z) = \sum_{n=0}^{\infty} V_{i,n}(x)z^{n},$$

$$i = 1, 2, \dots, k$$
(38)

$$V_{i}(0,z) = \sum_{n=0}^{\infty} V_{i,n}(0)z^{n},$$

$$i = 1,2,\dots,k$$
(39)

$$D_{i}(x, y, z) = \sum_{n=0}^{\infty} D_{i,n}(x, y) z^{n},$$

$$i = 1, 2, \dots, k$$
(40)

$$D_{i}(x,0,z) = \sum_{n=0}^{\infty} D_{i,n}(x,0)z^{n},$$

$$i = 1,2,\dots,k$$
(41)

$$R_{i}(x, y, z) = \sum_{n=0}^{\infty} R_{i,n}(x, y) z^{n},$$

$$i = 1, 2, \dots, k$$
(42)

$$R_{i}(x,0,z) = \sum_{n=0}^{\infty} R_{i,n}(x,0)z^{n},$$

$$i = 1,2,\dots,k$$
(43)

By multiplying equations (16)-(24) by z^n and summation on n, (44)-(48) are obtained:

$$\partial I(x,z)/\partial x + [\lambda \alpha_1 + \eta(x)]I(x,z) = 0$$
 (44)

$$\partial P_{i}(x,z)/\partial x + [\lambda + \mu_{i}(x) + \alpha_{i}]P_{i}(x,z)$$

$$= \lambda(1 - \alpha_{2})P_{i}(x,z)$$

$$+ \lambda\alpha_{2}C(z)P_{i}(x,z)$$

$$+ \int_{0}^{\infty} \varepsilon_{i}(y)R_{i}(x,y,z)dy$$
(45)

$$\frac{\partial V_i(x,z)}{\partial x} + [\lambda + \nu_i(x)]V_i(x,z)
= \lambda(1 - \alpha_3)V_i(x,z)
+ \lambda\alpha_3C(z)V_i(x,z)$$
(46)

$$\partial D_{i}(x, y, z) / \partial y + [\lambda + \gamma_{i}(y)] D_{i}(x, y, z)$$

$$= \lambda (1 - \alpha_{4}) D_{i}(x, y, z)$$

$$+ \lambda \alpha_{4} C(z) D_{i}(x, y, z)$$
(47)

$$\partial R_i(x, y, z) / \partial y + [\lambda + \varepsilon_i(y)] R_i(x, y, z)
= \lambda (1 - \alpha_5) R_i(x, y, z)
+ \lambda \alpha_5 C(z) R_i(x, y, z)$$
(48)

Theorem 1The PGFs for $|z| \le 1$ and i = 1, 2, ..., k are:

$$I(x,z) = I(0,z)[1 - A(x)]\exp(-\lambda \alpha_1 x)$$
 (49)

$$P_i(x, z) = P_i(0, z)[1 - B_i(x)] \exp(-xh_i(z))$$
 (50)

$$h_{i}(z) = \lambda \alpha_{2} (1 - C(z)) + a_{i} [1 - D_{i}^{*} (\lambda \alpha_{4} (1 - C(z)))] G_{i}^{*} (\lambda \alpha_{5} (1 - C(z)))$$
(51)

$$P_i(x, z) = P_i(0, z)[1 - B_i(x)] \exp(-xh_i(z))$$
 (52)

$$D_{i}(x, y, z) = D_{i}(x, 0, z)[1 - D_{i}(y)] \exp(-\lambda \alpha_{4}(1 - C(z))y)$$
(53)

$$R_i(x, y, z) = R_i(x, 0, z)[1$$

$$-G_i(y)] \exp(-\lambda \alpha_5(1 - C(z))y)$$
(54)

where

$$D_i^*(\lambda \alpha_4 (1 - C(z)))$$

$$= \int_0^\infty \exp(-\lambda \alpha_4 (1 - C(z))y) dD_i(y)$$

$$G_i^*(\lambda \alpha_4 (1 - C(z)))$$

$$= \int_0^\infty \exp(-\lambda \alpha_5 (1 - C(z))y) dG_i(y)$$

ProofBy solving the differential equations (44)-(48) the above relations can be obtained. For example, (50) has been obtained by using (45), as below:

$$\frac{\partial/\partial x}{P_i(x,z)} P_i(x,z) = -\left[\mu_i(x) + a_i + \lambda \alpha_2 + \lambda \alpha_2 C(z) + \frac{\int_0^\infty \varepsilon_i(y) R_i(x,y,z) dy}{P_i(x,z)}\right]$$

$$+ \frac{\int_0^\infty \varepsilon_i(y) R_i(x,y,z) dy}{P_i(x,z)}$$

$$= \int_0^\infty R_i(x,0,z) [1 - G_i(y)] \exp(-\lambda \alpha_5 (1 - G(z))y) \varepsilon_i(y) dy$$

$$= R_i(x,0,z) \int_0^\infty g_i(y) \exp(-\lambda \alpha_5 (1 - G(z))y) dy$$

$$= R_i(x,0,z) G_i^* \left(\lambda \alpha_5 (1 - G(z))\right)$$
also, by using (32):
$$R_i(x,0,z) = \int_0^\infty D_i(x,y,z) \gamma_i(y) dy$$

$$= \int_0^\infty D_i(x,0,z) [1 - D_i(y)] \exp(-\lambda \alpha_4 (1 - G(z))y) \gamma_i(y) dy$$

$$= D_i(x,0,z) D_i^* \left(\lambda \alpha_4 (1 - G(z))\right)$$

and by using (31):

$$\int_{0}^{\infty} \frac{\int_{0}^{\infty} \varepsilon_{i}(y) R_{i}(x, y, z) dy}{P_{i}(x, z)} dx$$

$$= \int_{0}^{\infty} \frac{a_{i} P_{i}(x, z) D_{i}^{*} \left(\lambda \alpha_{4} \left(1 - C(z)\right)\right) G_{i}^{*} \left(\lambda \alpha_{5} \left(1 - C(z)\right)\right)}{P_{i}(x, z)} dx$$

$$= a_{i} D_{i}^{*} \left(\lambda \alpha_{4} \left(1 - C(z)\right)\right) G_{i}^{*} \left(\lambda \alpha_{5} \left(1 - C(z)\right)\right) x$$

$$F_{i}(x, z)$$

$$= e^{-\int_{0}^{\infty} \mu_{i}(x) dx} exp\{\left[-a_{i} - \lambda \alpha_{2} \left(1 - C(z)\right)\right] x\} exp\left\{\int_{0}^{\infty} \frac{\int_{0}^{\infty} \varepsilon_{i}(y) R_{i}(x, y, z) dy}{P_{i}(x, z)} dx\right\}$$

and also, by using the formula (28) and (37),

$$P_i(0,z) = R_{i-1} X_{i-1}^* P_1(0,z)$$
(55)

sothat

$$X_i^* = \prod_{j=1}^i B_j^* \left(h_j(z) \right)$$

and

$$R_i = \prod_{j=1}^i \theta_j$$

$$\theta_0 = 1, \quad \theta_k = 0, \quad R_0 = 1, \quad R_k = 0$$

In addition, $P_1(0,z)$, $P_i(0,z)$, I(0,z), $V_i(0,z)$, $D_i(x,0,z)$ and $R_i(x,0,z)$ have been obtained as bellow:

$$P_1(0,z) = \sum_{n=0}^{\infty} P_{1,n}(0)z^n = \lambda c_1 I_0 + \int_0^{\infty} I_1(x)\eta(x)dx + \frac{1}{2} I_1(x) \eta(x)dx + \frac{$$

$$\sum_{n=1}^{\infty} P_{1,n}(0)z^n = \lambda I_0 \sum_{n=0}^{\infty} C_{n+1}z^n +$$

$$\int_0^{\infty} \sum_{n=0}^{\infty} I_{n+1}(x)z^n \eta(x)dx + \lambda \alpha_1 \sum_{n=0}^{\infty} \sum_{m=1}^{n} C_m \int_0^{\infty} z^n I_{n-m+1}(x)dx$$

$$zP_{1}(0,z)$$

$$= \lambda I_{0} \sum_{n=0}^{\infty} C_{n+1} z^{n+1} + \int_{0}^{\infty} \sum_{n=0}^{\infty} z^{n+1} I_{n+1}(x) \, \eta(x) dx$$

$$+ \lambda \alpha_{1} \sum_{m=1}^{n} C_{m} \int_{0}^{\infty} \sum_{n=1}^{\infty} z^{n+1} I_{n-m+1}(x) dx$$

$$= \lambda I_{0} C(z) + \int_{0}^{\infty} I(x,z) \eta(x) dx$$

$$+ \lambda \alpha_{1} \sum_{n=0}^{\infty} \sum_{m=1}^{n} C_{m} z^{m} \int_{0}^{\infty} z^{n-m+1} I_{n-m+1}(x) dx$$

$$= \lambda I_{0} C(z) + \int_{0}^{\infty} I(x,z) \eta(x) dx$$

$$+ \lambda \alpha_{1} C(z) \int_{0}^{\infty} I(x,z) dx$$

Now, by using (49) the bellow relation have been obtained:

$$= P_i(0, z)[1 - B_i(x)] \exp(-xh_i(z))$$

$$zP_{1}(0,z)$$

$$= \lambda I_{0}C(z)$$

$$+ I(0,z) \int_{0}^{\infty} [1$$

$$- A(x)] \exp(-\lambda \alpha_{1}x) \eta(x) dx$$

$$+ \lambda \alpha_{1}C(z)I(0,z) \int_{0}^{\infty} [1$$

$$- A(x)] \exp(-\lambda \alpha_{1}x) dx$$

$$= \lambda I_{0}C(z) + I(0,z)A^{*}(\lambda \alpha_{1})$$

$$+ \lambda \alpha_{1}C(z)I(0,z) \int_{0}^{\infty} [1$$

$$- A(x)] \exp(-\lambda \alpha_{1}x) dx$$

$$= \lambda I_{0}C(z)$$

$$+ I(0,z)\{A^{*}(\lambda \alpha_{1})$$

$$+ C(z)[1$$

$$- A^{*}(\lambda \alpha_{1})]\}$$

Also, by using (29), (30) and (55), $V_i(0, z)$ can be obtained:

$$V_{i}(0,z) = \sum_{n=0}^{\infty} V_{i,n}(0)z^{n}$$

$$= \int_{0}^{\infty} \tau_{i}[1 - \theta_{i} - p_{i}(1 - z)]P_{i}(x,z)\mu_{i}(x)dx$$

$$= \tau_{i}[1 - \theta_{i} - p_{i}(1 - z)]P_{i}(0,z)B_{i}^{*}(h_{i}(z))$$

$$= \tau_{i}[1 - \theta_{i} - p_{i}(1 - z)]P_{1}(0,z)R_{i-1}X_{i}^{*}$$
(57)

And by using (25) and (35):

$$\begin{split} I(0,z) &= \sum_{i=1}^k (1-\tau_i) p_i z \int_0^\infty \mu_i(x) P_i(x,z) dx + \\ &\sum_{i=1}^k (1-\tau_i) (1-\theta_i-p_i) \int_0^\infty \mu_i(x) P_i(x,z) dx + \\ &\sum_{i=1}^k \int_0^\infty \nu_i(x) V_i(x,z) dx - \lambda I_0 \end{split}$$

And by using (55) and (57):

$$\begin{split} I(0,z) &= P_1(0,z) \sum_{i=1}^k \{(1-\tau_i)p_iz + (1-\tau_i)(1-\theta_i-p_i) + \tau_i[1-\theta_i-p_i(1-z)]\} R_{i-1}X_i^* - \lambda I_0 \\ &= P_1(0,z)F(z) - \lambda I_0 \end{split}$$

Now, by substituting $P_1(0, z)$ from (56), I(0, z) can be obtained:

$$I(0,z) = \frac{\lambda I_0[C(z)F(z) - z]}{z - F(z)[A^*(\lambda\alpha_1) + C(z)(1 - A^*(\lambda\alpha_1))]}$$

In witch,

$$F(z) = \sum_{i=1}^{k} \{ (1 - \tau_i) p_i z + (1 - \tau_i) (1 - \theta_i - p_i) + \tau_i [1 - \theta_i - p_i (1 - z)] \} R_{i-1} X_i^*$$

Obtaining relations $R_i(x, 0, z)$ and $D_i(x, 0, z)$ has already been discussed before.

Theorem 2

Under the steady state condition, the joint distributions of the server state have the following partial generating functions:

$$I(z) = \lambda I_0 \frac{[C(z)F(z) - z][1 - A^*(\lambda \alpha_1)]}{\lambda \alpha_1 \{z - F(z)[A^*(\lambda \alpha_1) + C(z)(1 - A^*(\lambda \alpha_1))]\}}$$
(58)

$$P_{i}(z) = \lambda I_{0} \frac{A^{*}(\lambda \alpha_{1})[C(z) - 1][1 - B_{i}^{*}(h_{i}(z))]R_{i-1}X_{i-1}^{*}}{h_{i}(z)\{z - F(z)[A^{*}(\lambda \alpha_{1}) + C(z)(1 - A^{*}(\lambda \alpha_{1}))]\}}$$
(59)

$$\begin{aligned} &V_{i}(z) \\ &= \lambda I_{0} \frac{\tau_{i} [1 - \theta_{i} - p_{i}(1 - z)] \left[1 - V_{i}^{*} \left(\lambda \alpha_{3} \left(1 - C(z) \right) \right) \right] B_{i}^{*} \left(h_{i}(z) \right) h}{\lambda \alpha_{3} \left(1 - C(z) \right) \left[1 - B_{i}^{*} \left(h_{i}(z) \right) \right]} \end{aligned} \tag{60}$$

$$D_i(z) = a_i \frac{\left[1 - D_i^* \left(\lambda \alpha_4 (1 - C(z))\right)\right]}{\lambda \alpha_4 (1 - C(z))} P_i(z)$$
(61)

$$R_{i}(z) = a_{i} \frac{D_{i}^{*} \left(\lambda \alpha_{4} \left(1 - C(z)\right)\right) \left[1 - G_{i}^{*} \left(\lambda \alpha_{5} \left(1 - C(z)\right)\right)\right]}{\lambda \alpha_{5} \left(1 - C(z)\right)} P_{i}(z)$$
(62)

Proof The partial generating functions I(z), $P_i(z)$, $V_i(z)$, $D_i(z)$ and $R_i(z)$ are defined as follow:

$$I(z) = \int_0^\infty I(x, z) dx \tag{63}$$

$$P_i(z) = \int_0^\infty P_i(x, z) dx,\tag{64}$$

$$V_i(z) = \int_0^\infty V_i(x, z) dx. \tag{65}$$

$$D_i(z) = \int_0^\infty \int_0^\infty D_i(x, y, z) \, dx dy. \tag{66}$$

$$D_i(z) = \int_0^\infty \int_0^\infty D_i(x, y, z) \, dx dy. \tag{66}$$

$$R_i(z) = \int_0^\infty \int_0^\infty R_i(x, y, z) \, dx dy. \tag{67}$$

By substituting the equations (49)-(54) in these formulas, the relation in equation (58)-(62) can be obtained.

Also, to find I_0 , the normalizing condition can be used

$$= \frac{1 - F'(1) - \left(1 - A^*(\lambda \alpha_1)\right)C[1]}{1 - F'(1) + \lambda C[1] \sum_{i=1}^{k} \left\{R_{i-1}b_{i1}\left[a_ig_{i1} + a_id_{i1} - \tau_i(1 - \theta_i)\frac{\nu_{i1}}{b_{i1}} - 1\right]\right\}}$$

(68)

System performance measures

In this section, some essential performance measures are derived. For this, the partial generating functions of the number of customers in the system and in orbit are introduced. Then by differentiating of these functions, the means of system and orbit size are obtained.

Proposition

a) The PGF of the number of customers in the system is

$$\Omega(z) = I_0 \frac{\left[C(z)F(z) - z\right]\left[1 - A^*(\lambda\alpha_1)\right] + \alpha_1 \left\{z - F(z)\left[A^*(\lambda\alpha_1) + C(z)\left(1 - A^*(\lambda\alpha_1)\right)\right] + A^*(\lambda\alpha_1)W(z)\right\}}{\alpha_1 \left\{z - F(z)\left[A^*(\lambda\alpha_1) + C(z)\left(1 - A^*(\lambda\alpha_1)\right)\right]\right\}}$$
(69)

where

$$W(z) = \sum_{i=1}^{k} \frac{R_{i-1}X_{i-1}^{*}}{\alpha_{3}\alpha_{4}\alpha_{5}} \left\{ \alpha_{3} \left[1 - B_{i}^{*} \left(h_{i}(z) \right) \right] \left\{ z\alpha_{4}\alpha_{5} + a_{i}\alpha_{5} \left[1 - D_{i}^{*} \left(\lambda\alpha_{4} \left(1 - C(z) \right) \right) \right] + a_{i}\alpha_{4}D_{i}^{*} \left(\lambda\alpha_{4} \left(1 - C(z) \right) \right) \left[1 - G_{i}^{*} \left(\lambda\alpha_{5} \left(1 - C(z) \right) \right) \right] \right\} + \alpha_{4}\alpha_{5}\tau_{i} \left[1 - \theta_{i} - p_{i}(1 - z) \right] \left[1 - V_{i}^{*} \left(\lambda\alpha_{3} \left(1 - C(z) \right) \right) \right] B_{i}^{*} \left(h_{i}(z) \right) h_{i}(z) \right\}$$

The PGF of the number of customers in orbit is

$$\varphi(z) = I_0 \frac{\left[C(z) F(z) - z \right] \left[1 - A^*(\lambda \alpha_1) \right] + \alpha_1 \left\{ z - F(z) \left[A^*(\lambda \alpha_1) + C(z) \left(1 - A^*(\lambda \alpha_1) \right) \right] + A^*(\lambda \alpha_1) U(z) \right\}}{\alpha_1 \left\{ z - F(z) \left[A^*(\lambda \alpha_1) + C(z) \left(1 - A^*(\lambda \alpha_1) \right) \right] \right\}}$$
(70)

where

$$\begin{split} U(z) &= \sum_{i=1}^{k} \frac{R_{i-1} X_{i-1}^{*}}{\alpha_{3} \alpha_{4} \alpha_{5}} \Big\{ \alpha_{3} \Big[1 - B_{i}^{*} \Big(h_{i}(z) \Big) \Big] \Big\{ \alpha_{4} \alpha_{5} + a_{i} \alpha_{5} \Big[1 - D_{i}^{*} \Big(\lambda \alpha_{4} \Big(1 - C(z) \Big) \Big) \Big] \\ &+ a_{i} \alpha_{4} D_{i}^{*} \Big(\lambda \alpha_{4} \Big(1 - C(z) \Big) \Big) \Big[1 - G_{i}^{*} \Big(\lambda \alpha_{5} \Big(1 - C(z) \Big) \Big) \Big] \Big\} \\ &+ \alpha_{4} \alpha_{5} \tau_{i} \Big[1 - \theta_{i} - p_{i} (1 - z) \Big] \Big[1 - V_{i}^{*} \Big(\lambda \alpha_{3} \Big(1 - C(z) \Big) \Big) \Big] B_{i}^{*} \Big(h_{i}(z) \Big) h_{i}(z) \Big\} \end{split}$$

Corollary

a) The mean system size is:

$$L_s = I_0 \times \lim_{z \to 1} \frac{f'/g' - g'/f'}{2[g']^2},\tag{71}$$

in which

$$\begin{split} g(z) &= \alpha_1 \big\{ z - F(z) \big[A^*(\lambda \alpha_1) + C(z) \big(1 - A^*(\lambda \alpha_1) \big) \big] \big\} \\ g'(z) &= \alpha_1 \big\{ 1 - F'(z) \big[A^*(\lambda \alpha_1) + C(z) \big(1 - A^*(\lambda \alpha_1) \big) \big] - C'(z) F(z) \big(1 - A^*(\lambda \alpha_1) \big) \big\} \\ \lim_{z \to 1} g'(z) &= \alpha_1 \big\{ 1 - F'(1) - C_{[1]} \big(1 - A^*(\lambda \alpha_1) \big) \big\} \\ g''(z) &= \alpha_1 \big\{ - F''(z) \big[A^*(\lambda \alpha_1) + C(z) \big(1 - A^*(\lambda \alpha_1) \big) \big] - 2C'(z) F'(z) \big(1 - A^*(\lambda \alpha_1) \big) - C''(z) F(z) \big(1 - A^*(\lambda \alpha_1) \big) \big\} \\ \lim_{z \to 1} g''(z) &= \alpha_1 \big\{ - F''(1) - 2C_{[1]} F'(1) \big(1 - A^*(\lambda \alpha_1) \big) - C_{[2]} \big(1 - A^*(\lambda \alpha_1) \big) \big\} \end{split}$$

$$\begin{split} F(z) &= \sum_{i=1}^{k} \{(1-\tau_i)p_iz + (1-\tau_i)(1-\theta_i-p_i) + \tau_i[1-\theta_i-p_i(1-z)]\} R_{i-1}X_i^* \\ &\lim_{z\to 1} F(z) = 1 \\ F'(z) &= \sum_{i=1}^{k} \{(1-\tau_i)p_i + \tau_ip_i\} R_{i-1}X_i^* \\ &\quad + \sum_{i=1}^{k} \{(1-\tau_i)p_iz + (1-\tau_i)(1-\theta_i-p_i) + \tau_i[1-\theta_i-p_i(1-z)]\} R_{i-1}X_{i-1}^* \\ &\lim_{z\to 1} \frac{d}{dz} X_i^* = \sum_{j=1}^{k} h_j^t(1) b_{j1} \\ h_i(z) &= \lambda a_2(1-C(z)) + a_i[1-D_i^t(\lambda a_4(1-C(z)))] G_i^t(\lambda a_5(1-C(z))) \\ h_i^t(z) &= -\lambda a_2C^t(z) + a_i\lambda a_4C^t(z) \frac{d}{dz} b_i^t(\lambda a_4(1-C(z))) G_i^t(\lambda a_5(1-C(z))) \\ &- a_i\lambda a_5C^t(z) b_i^t(\lambda a_4(1-C(z))) \frac{d}{dz} G_i^t(\lambda a_5(1-C(z))) \\ h_i^t(1) &= \lim_{z\to 1} \frac{d}{dz^2} h_i^t(z) \\ h_i^t(1) &= \lim_{z\to 1} \frac{d^2}{dz^2} h_i(z) - \sum_{i=1}^{k} (R_{i-1}-R_i) \frac{d}{dz} X_{i-1}^* \\ &= \sum_{i=1}^{k} \sum_{j=1}^{i-1} (R_{i-1}-R_i) \lambda C_{[1]}(a_2+a_i(a_4d_{i1}+a_5g_{i1}))b_{j1} \\ \lim_{z\to 1} F'(z) &= \sum_{i=1}^{k} p_i R_{i-1} \sum_{j=1}^{k} b_{j1} h_j^t(1) + \sum_{i=1}^{k} \sum_{j=1}^{i-1} (R_{i-1}-R_i) \left[b_{j1} h_j^t/(1) + b_{j2}(h_j^t(1))^2\right] \\ h_j^t/(1) &= -C_{[2]} \lambda a_2 - C_{[2]} \lambda a_i(a_4d_{i1}+a_5g_{i1}) + C_{[1]}^2 \lambda^2 a_i(a_4^2d_{i2}+a_5^2g_{i2}+2a_4a_5d_{i1}g_{i1}) \\ f(z) &= \left[C(z)F(z)-z\right] [1-A^*(\lambda a_1)] + a_1\{z-F(z)[A^*(\lambda a_1)+C(z)(1-A^*(\lambda a_1))] + A^*(\lambda a_1)M^t(z)\right] \\ f''(z) &= \left[C'(z)F(z)+C(z)F'(z)-1\right] (1-A^*(\lambda a_1)) \\ &+ a_1\{1-F'(z)[A^*(\lambda a_1)+C(z)(1-A^*(\lambda a_1))] - C'(z)F(z)(1-A^*(\lambda a_1)) + A^*(\lambda a_1)M^t(z)\right] \\ f''(z) &= \left[C''(z)F(z)+2C'(z)F'(z)+C(z)F'(z)\right] (1-A^*(\lambda a_1)) - A_2(C'(z)F'(z)(1-A^*(\lambda a_1)) + A^*(\lambda a_1)M^t(z)\right] \\ f'''(z) &= \left[C''(z)F(z)+2C'(z)F'(z)+C(z)F'(z)\right] (1-A^*(\lambda a_1)) - C'(z)F'(z)\left(1-A^*(\lambda a_1)\right) - F(z)C''(z)\left(1-A^*(\lambda a_1)\right) + A^*(\lambda a_1)M^t(z)\right] \\ f'''(1) &= \lim_{z\to 1} f''(2) &= \left[C(1-a_1)\left[C_{[2]}+2F'(1)C_{[1]}\right] + F''(1)\left[1-A^*(\lambda a_1)\right) + a_1[W''(1)A^*(\lambda a_1)-F''(1)\right] \\ f'''(1) &= \lim_{z\to 1} f''(2) &= \left[C(1-a_1)\left[C_{[2]}+2F'(1)C_{[1]}\right] + F''(1)\left[1-A^*(\lambda a_1)\right) + a_1[W''(1)A^*(\lambda a_1)-F''(1)\right] \\ f'''(1) &= \lim_{z\to 1} f''(2) &= \left[C(1-a_1)\left[C_{[2]}+2F'(1)C_{[1]}\right] + F''(1)\left[1-A^*(\lambda a_1)\right) + a_1[W''(1)A^*(\lambda a_1)-F''(1)\right] \\ f'''(1) &= \lim_{z\to 1} f''(2) &= \left[C(1-a_1)\left[C_{[2]}+2F'(1)C_{[1]}\right] + F''(1)\left[1-$$

$$\begin{split} W(z) &= \sum_{i=1}^{k} \frac{R_{i-1}X_{i-1}^{*}}{\alpha_{3}\alpha_{4}\alpha_{5}} \Big\{ \alpha_{3} \Big[1 - B_{i}^{*} \Big(h_{i}(z) \Big) \Big] \Big\{ z\alpha_{4}\alpha_{5} + a_{i}\alpha_{5} \Big[1 - D_{i}^{*} \Big(\lambda\alpha_{4} \Big(1 - C(z) \Big) \Big) \Big] \Big\} \\ &\quad + a_{i}\alpha_{4}D_{i}^{*} \Big(\lambda\alpha_{4} \Big(1 - C(z) \Big) \Big) \Big[1 - G_{i}^{*} \Big(\lambda\alpha_{5} \Big(1 - C(z) \Big) \Big) \Big] \Big\} \\ &\quad + \alpha_{4}\alpha_{5}\tau_{i} \Big[1 - \theta_{i} - p_{i}(1 - z) \Big] \Big[1 - V_{i}^{*} \Big(\lambda\alpha_{3} \Big(1 - C(z) \Big) \Big) \Big] B_{i}^{*} \Big(h_{i}(z) \Big) h_{i}(z) \Big\} \\ W'(z) &= \frac{dW(z)}{dz} \\ W'(1) &= \lim_{z \to 1} W'(z) = -\sum_{i=1}^{k} R_{i-1} \left[h_{i}^{\prime} \Big(1 \Big) b_{i1} + \frac{\tau_{i} \Big(1 - \theta_{i} \Big)}{\alpha_{3}} v_{i1} \right] \\ W''(1) &= \lim_{z \to 1} W''(z) \\ &= -2 \sum_{i=1}^{k} \frac{dX_{i-1}^{*}}{dz} R_{i-1} \left[h_{i}^{\prime} \Big(1 \Big) b_{i1} - \frac{\tau_{i} \Big(1 - \theta_{i} \Big)}{\alpha_{3}} v_{i1} \right] \\ &\quad + \sum_{i=1}^{k} \frac{R_{i-1}}{\alpha_{3}\alpha_{4}\alpha_{5}} \Big\{ -\alpha_{3}\alpha_{4}\alpha_{5} \left[h_{i}^{\prime\prime} \Big(1 \Big) b_{i1} + \Big(h_{i}^{\prime} \Big(1 \Big) \Big)^{2} b_{i2} - 2h_{i}^{\prime} \Big(1 \Big) b_{i1} \Big] \Big\} + 2\alpha_{3}h_{i}^{\prime} \Big(1 \Big) a_{i}b_{i1} \Big(\alpha_{5}d_{i1} + \alpha_{4}g_{i1} \Big) \\ &\quad - 2\alpha_{4}\alpha_{5}\tau_{i}v_{i1} \Big\{ p_{i} + \Big(1 - \theta_{i} \Big) \left[h_{i}^{\prime} \Big(1 \Big) + b_{i1} \right] - \alpha_{4}\alpha_{5}\tau_{i}v_{i2} \Big(1 - \theta_{i} \Big) \Big\} \end{split}$$

b) The mean orbit size is:

$$L_q = I_0 \times \lim_{z \to 1} \frac{m^{//}(z)g^{/}(z) - g^{//}(z)m^{/}(z)}{2[g^{/}(z)]^2},$$
(72)

in which

$$\begin{split} m(z) &= [C(z)F(z) - z][1 - A^*(\lambda\alpha_1)] + \alpha_1 \big\{ z - F(z) \big[A^*(\lambda\alpha_1) + C(z) \big(1 - A^*(\lambda\alpha_1) \big) \big] + A^*(\lambda\alpha_1) U(z) \big\} \\ m'(z) &= \big\{ C'(z)F(z) + C(z)F'(z) - 1 \big\} \big(1 - A^*(\lambda\alpha_1) \big) \\ &+ \alpha_1 \big\{ 1 - F'(z) \big[A^*(\lambda\alpha_1) + C(z) \big(1 - A^*(\lambda\alpha_1) \big) \big] - C'(z)F(z) \big(1 - A^*(\lambda\alpha_1) \big) + A^*(\lambda\alpha_1) U'(z) \big\} \\ m'(1) &= \lim_{z \to 1} m'(z) = \big[C_{[1]} + F'(1) - 1 \big] \big(1 - A^*(\lambda\alpha_1) \big) + \alpha_1 \big\{ 1 - F'(1) - C_{[1]} \big(1 - A^*(\lambda\alpha_1) \big) + A^*(\lambda\alpha_1) U'(1) \big\} \\ m''(z) &= \big\{ C''(z)F(z) + 2C'(z)F'(z) + C(z)F''(z) \big\} \big(1 - A^*(\lambda\alpha_1) \big) \\ &+ \alpha_1 \big\{ F''(z) \big[A^*(\lambda\alpha_1) + C(z) \big(1 - A^*(\lambda\alpha_1) \big) \big] - 2C'(z)F'(z) \big(1 - A^*(\lambda\alpha_1) \big) \\ &- F(z)C''(z) \big(1 - A^*(\lambda\alpha_1) \big) + A^*(\lambda\alpha_1) U''(z) \big\} \\ m''(1) &= \lim_{z \to 1} m''(z) = \big\{ (1 - \alpha_1) \big[C_{[2]} + 2F'(1) C_{[1]} \big] + F''(1) \big\} \big(1 - A^*(\lambda\alpha_1) \big) + \alpha_1 \big[U''(z) A^*(\lambda\alpha_1) - F''(1) \big] \end{split}$$

$$\begin{split} U'(z) &= \frac{dU(z)}{dz} \\ U'(1) &= \lim_{z \to 1} U'(z) = -\sum_{i=1}^k R_{i-1} \left[h_i'(1)b_{i1} + \frac{\tau_i(1 - \theta_i)}{\alpha_3} \nu_{i1} \right] \\ U''(1) &= \lim_{z \to 1} U''(z) \\ &= -2 \sum_{i=1}^k \frac{dX_{i-1}^*}{dz} R_{i-1} \left[h_i'(1)b_{i1} + \frac{\tau_i(1 - \theta_i)}{\alpha_3} \nu_{i1} \right] \\ &+ \sum_{i=1}^k \frac{R_{i-1}}{\alpha_3 \alpha_4 \alpha_5} \left\{ -\alpha_3 \alpha_4 \alpha_5 \left[h_i''(1)b_{i1} + \left(h_i'(1) \right)^2 b_{i2} \right] \right\} + 2\alpha_3 h_i'(1)a_i b_{i1}(\alpha_5 d_{i1} + \alpha_4 g_{i1}) \\ &- 2\alpha_4 \alpha_5 \tau_i \nu_{i1} \left\{ p_i + (1 - \theta_i) \left[h_i'(1) + b_{i1} \right] \right\} - \alpha_4 \alpha_5 \tau_i \nu_{i2} (1 - \theta_i) \end{split}$$

Proof of corollary

By differentiating of the $\Omega(z)$ in (69), taking limit at z = 1 and applying L'Hopital rule we have

$$L_{\rm s} = \lim_{z \to 1} d\Omega(z)/dz$$
.

 $L_{\rm S}=\lim_{z\to 1}d\Omega(z)/dz.$ By differentiating of the $\phi(z)$ in (70), taking limit at z = 1 and applying L'hopital rule we have

$$L_q = \lim_{z \to 1} d\phi(z)/dz.$$

In follow, we can obtain the mean of waiting time of customers at the system and orbit by using Little's formula and relations (71) and (72) as follows:

$$W_s = L_s/\lambda$$
, and $W_q = L_q/\lambda$.

The Numerical Example (The inspection test of valves)

In this section, the results of a numerical example are shown in a specific case of this model.

The inspection process of a valve producer can be considered as an application of this model. The valves are used at several engineering systems, thus their quality and inspection processes are very important for them. This process can be done in 3 phases (Table 1). So, the valves are sent to a station individually with Poisson distribution with rate λ per hour. It is possible to inspect all the valves($\alpha_i = 1, i = 1,2,3,4,5$). Also the retrial times in this process have an exponential distribution with rate η per hour. The vacation is occurred at the end of third phase and the vacation times are distributed exponential with mean v₃ (min). In this example, the probability of failure is considered zero, so the effect of delay and repair variables is not examined.

Table 1.The values of the parameters of model for quality control of valves

Number of phases (i)	Name of phases	Distribution of service times	Mean of service times (min)	The probability of pass of the phase $(\theta_i, i = 1, 2 \text{ and } q_{3})$ (Three cases are considered for different value of reliability)			p_i			$ au_i$
1	Painting inspection	Exponential(Exp)	3	0.999999	0.8	0.65	0.1			0
2	Pressure tests	Exp	5	0.999999	0.8	0.65	0.1			0
3	Operation inspection manual operating type	Exp	10	0.999999	0.8	0.65	1-10 ⁻⁶	0.2	0.35	0.1

Then, the results of the sensitivity analysis of the test inspection respect to the values of λ , η and v_3 at different values of reliability in the Fig. 1., Fig. 2. and Fig. 3., in the following:

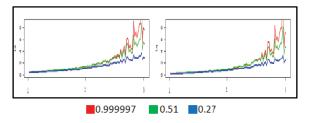


Figure 1. Performance measures for various values of λ ([1,3]) and RE when $\eta = 10$ and $v_3 = 6$

As Figure 1 shows, L_s and L_q experience an increasing trend, when λ tends to increase.

Figure 2 demonstrates that, L_s and L_q experience a decreasing trend, when η increases.

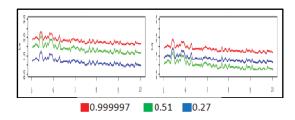


Figure 2. Performance measures for various values of η ([5,10]) and RE when $\lambda = 2$ and $v_3 = 6$

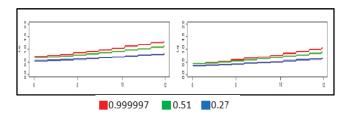


Figure 3. Performance measures for various values of v_3 ([6,12]) and RE when $\lambda = 2and\eta = 10$

It seems from Figure 3 that, L_s and L_q experience an increasing trend when ν tends to increase.

Also, Figure 1, 2 and 3 show that, by increasing the value of reliability, the L_s and L_q are increased.

Thus, the r_i and q_3 probabilities (i = 1,2), should be increased to reliability increasing. Consequently, the following comments can help to increase reliability.

- (1) The casting process output has to be tested.
- (2) Raw materials used for stem valves manufacturing, should be evaluated and controlled.
- (3) According to the experiment and experts comment, all fastens and connections should be checked by standard gauges. This task improves flanges quality and reduces the rejection rate.
- (4) Checking punches of valves after assembly by using Bench test

Conclusion

In thispaper, $aM^X/G/1$ retrial queueing model with first essential phase and k-1 optional phases of service, probabilistic feedback, failure, delay, repair, and vacation conditions at each phase is considered. For this model, the steady-state equations, the generating functions of the number of customers in the system and orbit, and some important performance measures such as the mean of the system and orbit size and the mean of the system and orbit waiting times have been derived by the supplementary variable technique. Then, in a specificcase of this model, the sensitivity analysis of performance measures via model parameters in different values of the reliability is conducted. According to the results of this analysis, some technical suggestions are presentedfor managing the parameters of the model in order to control and optimize the performance of the system. In the future researches, the modeling and analyzing multi-stage systems with several servers and the systems which their service phases times are dependent can be considered.

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